

## Numerical Analysis Preliminary Examination, August 2013

Work **all six** of the following problems.

1. Consider a nonsingular matrix  $A \in \mathbb{C}^{n \times n}$ .

- Write out the steps of the (“pure” unshifted) QR algorithm for finding the eigenvalues of  $A$ .
- Show that each of the matrices  $A_k$  generated by the QR algorithm is unitarily similar to  $A$ .
- Show that if  $A$  is upper Hessenberg, then so are each of the matrices  $A_k$  generated by the QR algorithm.
- Describe an algorithm for computing an SVD of  $A$  using the eigenvalue decomposition of a related matrix.

2. Let  $A$  be the  $3 \times 3$  matrix be

$$A = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 5 & 5 \\ 3 & 5 & 14 \end{bmatrix}$$

- Compute the Cholesky factorization of  $A$ .
- Let  $U$  be an  $n \times n$  upper triangular matrix with no zeros on the diagonal, and let  $b$  be a vector in  $\mathbb{R}^n$ . Derive the exact number of floating point operations required to solve the triangular system of equations  $Ux = b$  for  $x$ .

3. Estimate the numerical value of the integral

$$I = \int_{-1}^1 \frac{dx}{1+x^4}$$

with three-point Gauss-Legendre quadrature.

4. Let  $p_N$  be the best  $N$ -th degree polynomial approximation to a real-valued function  $f \in L^2[0, 1]$  in the norm

$$\|v\|_2 = \sqrt{\int_0^1 v^2 dx}.$$

- Compute the best first-degree polynomial approximation to  $f(x) = x^2$ .
- Let  $N = 1$ , and suppose that  $f$  is continuous. Prove that there is at least one point  $\xi \in [0, 1]$  such that  $p_1(\xi) = f(\xi)$ .
- Suppose  $f \in C^{N+1}[0, 1]$ . Derive an estimate for the uniform norm

$$\|p_N(x) - f(x)\|_\infty.$$

You may use, without proof, the generalization of (b) to  $N > 1$ : there are at least  $N$  distinct points  $x_i \in [0, 1]$  such that  $p_N(\xi_i) = f(\xi_i)$ .

5. Consider numerical solution of the initial value problem  $y' = f(t, y)$ ,  $y(0) = y_0$  with stepsize  $h$ .

A step of the *theta method* is as follows:

$$t_{n+1} = t_n + h$$

$$y_{n+1} = y_n + \theta h f(t_n, y_n) + (1 - \theta) h f(t_{n+1}, y_{n+1})$$

where  $\theta$  is a constant parameter in the interval  $[0, 1]$ .

- (a) After making the minimum necessary assumptions about the differentiability of  $f$ , find the *order of accuracy* for this method as a function of  $\theta$ . State your differentiability assumptions clearly. Note that your answer will depend on  $\theta$ .
- (b) Clearly state the definitions of absolute stability and A-stability. For what (if any) values of  $\theta$  is this method A-stable?
6. Consider the fixed point iteration  $x_{k+1} = g(x_k)$ , where

$$g(x) = \tan^{-1}(2x).$$

- (a) Clearly  $g(x)$  has a fixed point at  $x = 0$ . Show that the fixed point iteration will not converge to this fixed point.
- (b) There is another fixed point  $x_*$  near  $x = 1.166$ . Find an appropriate interval about  $x_*$  and prove that the fixed point iteration will converge to  $x_*$  for any initial guess  $x_0$  in this interval. [Hint:  $\tan^{-1}(2) \approx 1.107$ .]
- (c) Write out a step of Newton's method for finding  $x_*$ . (You do not need to show convergence for Newton's method.)