

## SPRING 2011 ODE/PDE PRELIMINARY EXAM

DO 3 PROBLEMS FROM PART I AND 3 PROBLEMS FROM PART II. YOU MUST CLEARLY INDICATE WHICH 6 PROBLEMS ARE TO BE GRADED. GIVE A FULL STATEMENT OF THE THEOREMS USED IN PROVING THE RESULTS.

### PART I: ODE

1. Consider the linear time invariant system of equations:

$$\begin{aligned}\dot{x}_1 &= A_{11}x_1 + A_{12}x_2 \\ \dot{x}_2 &= A_{21}x_1 + A_{22}x_2,\end{aligned}\tag{1}$$

where  $A_{11}$  is an  $n_1 \times n_1$  matrix and  $A_{22}$  is an  $n_2 \times n_2$  matrix.

- (a) State La Salle's invariance principle.
- (b) Suppose there exists an  $n_1 \times n_1$  constant matrix  $P$  such that

$$A_{11}^T P + P A_{11} = -I.\tag{2}$$

Prove that  $P$  must be non-singular.

- (c) Suppose that there exists a constant matrix  $P$  satisfying (2). Use the function  $V(x_1) = x_1^T P x_1$  to prove that the origin  $x_1 = 0$  is locally asymptotically stable for the system

$$\dot{x}_1 = A_{11}x_1.\tag{3}$$

- (d) Suppose that there exists a  $P$  satisfying (2). Further suppose that there exists an  $n_2 \times n_2$  constant matrix  $Q$  such that

$$A_{22}^T Q + Q A_{22} = -I.\tag{4}$$

Use  $V(x_1, x_2) = x_1^T P x_1 + x_2^T Q x_2$  to prove that the origin  $(x_1, x_2) = (0, 0)$  for the system (1) is locally asymptotically stable provided  $\|A_{12}\|$  and  $\|A_{21}\|$  are sufficiently small.

2. Consider the two dimensional system:

$$\begin{aligned}\frac{dx}{dt} &= -y + x(1 - x^2 - y^2) \\ \frac{dy}{dt} &= x + y(1 - x^2 - y^2).\end{aligned}$$

- (a) Show that the set  $S = \{(x, y) \mid x^2 + y^2 = 1\}$  is an invariant set for the system. This means that if the initial point  $(x_0, y_0)$  is in the set  $S$ , then the solution trajectory lies in  $S$ .
- (b) Show that for an initial condition in  $S$  the solution is of the form:  $x(t) = \cos(\omega t + \phi)$  and  $y(t) = \sin(\omega t + \phi)$ , where  $\omega > 0$  and  $\phi \in [0, 2\pi)$ . What is the value of  $\omega$ ?
- (c) Obtain the equations of the system in polar coordinates. Using these equations, show that the set  $S$  is an  $\omega$  limit set - that is, every trajectory except the zero trajectory spirals towards this set as  $t \rightarrow \infty$ .

3. Consider the ODE:

$$\frac{d^2y}{dt^2}(t) + t^{-1} a_1 \frac{dy}{dt}(t) + t^{-2} a_0 y(t) = 0, \quad (5)$$

where  $a_0$  and  $a_1$  are constants.

(a) Write the ODE in the form:

$$\frac{dx}{dt} = t^{-1} A x, \quad (6)$$

where  $A$  is a constant matrix, and  $x$  is a vector.

- (b) For a scalar  $t > 0$  and a constant square matrix  $A$ , define  $t^A = e^{A \ln(t)}$ . Show that the solution of (6) is of the form:  $x(t) = t^A x_0$  where  $x_0 = x(1)$ . *Hint:* Re-parameterize the variable  $t$  and rewrite (6) in terms of the new variable.
- (c) Prove that for scalars  $t_1, t_2 > 0$ , we have:

$$t_1^A t_2^A = (t_1 t_2)^A.$$

*Hint:* Use any properties of the exponential of a matrix you know.

(d) Prove that for  $t > 0$ :

$$\det(t^A) = t^{\text{trace}(A)}.$$

4. Show that the origin is locally asymptotically stable for the system

$$\dot{x}_1 = -\sin(x_1) + x_1x_2^2, \quad \dot{x}_2 = -x_2 - x_1^2x_2. \quad (7)$$

State clearly any theorem you use to prove your claim.

## PART II: PDE

5. Given  $L > 0$ . Let  $u_T(x, t)$ ,  $T > 0$ , be a classical solution of the initial value problem:

$$(u_T)_t = (u_T)_{xx}, \quad 0 < x < L, \quad t > 0,$$

$$u_T(0, t) = u_T(L, t) = 0, \quad t > 0$$

$$u_T(x, -T) = 1, \quad 0 < x < L.$$

- (a) Prove that for  $t > -T$

$$\frac{d}{dt} \int_0^L u_T^2(x, t) dx \leq - \int_0^L (u_T)_x^2(x, t) dx.$$

- (b) Prove that there exists a positive constant  $C$  such that

$$C \int_0^L u_T^2(x, t) dx \leq \int_0^L (u_T)_x^2(x, t) dx.$$

- (c) Prove that

$$\int_0^L u_T^2(x, t) dx \rightarrow 0 \text{ as } t \rightarrow \infty.$$

6. Let  $U$  be an open subset of  $\mathbb{R}^n$  and let  $u \in C^2(U) \cap C(\bar{U})$  be a classical non-negative solution of the equation

$$\Delta u + cu = 0 \quad \text{in } U,$$

where  $c$  is a positive number.

- (a) Find a function  $f(r)$ ,  $r \geq 0$ , such that  $\lim_{r \rightarrow 0} f(r) = 0$  and the function  $v(x) = u(x) + Mf(|x|)$  is subharmonic in  $U$ , that is,  $-\Delta v \leq 0$  in  $U$ . Here  $M = \max_{\bar{U}} u$ .

- (b) Show that there is  $R > 0$  such that if  $U \subset \{x \in \mathbb{R}^n : |x| < R\}$  then

$$\max_{\bar{U}} u \leq 2 \max_{\partial U} u.$$

7. Let  $U$  be an open, bounded subset of  $\mathbb{R}^n$  with  $C^2$  boundary. Let  $u(x, t)$  be a classical solution of the initial boundary value problem

$$u_{tt} + k(x, t)u_t = \operatorname{div}(a(x)\nabla u), \quad x \in U, \quad t > 0,$$

$$u = \phi(x, t), \quad x \in \partial U, \quad t > 0,$$

$$u(x, 0) = f(x), \quad u_t(x, 0) = g(x), \quad x \in U,$$

where  $k(x, t)$ ,  $a(x)$ ,  $g(x)$ ,  $f(x)$ ,  $\phi(x, t)$  are smooth functions.

Prove that if  $k(x, t) \geq 0$  and  $0 < c \leq a(x, t) \leq C < \infty$  for all  $(x, t)$ , then the above solution  $u(x, t)$  is unique.

8. Solve the equation

$$u_x u_y = 3 \quad \text{on } U = \{(x, y) \in \mathbb{R}^2 : x > 0\},$$

$$u(x, 0) = \log x, \quad x > 0,$$

where  $u = u(x, y)$ , and  $\log$  denotes the natural logarithm.